Name:

**Enrolment No:** 

## **UPES**

## **UNIVERSITY OF PETROLEUM AND ENERGY STUDIES**

## End Semester Examination, Nov-Dec 2021

**SECTION A** 

Programme Name: B.Tech. Mechanical Engineering

**Course Name** : Instrumentation and Control

**Course Code** : ECEG3011

Nos. of page(s) :03

Instructions: 1. Assume any missing data

2. Section B has an internal choice in Q.9.

3. Section C has an internal choice in Q.10.

(Answer in not more than 50 words)						
S. No.		Marks	CO			
Q 1	Discuss the components of a closed-loop control system.	4	<b>CO1</b>			
Q 2	Describe the methods for performing frequency response analysis of control systems.	4	<b>CO4</b>			
Q 3	Describe any four static characteristics of a measurement instruments.	4	CO1			
Q 4	Discuss the significance of dynamic characteristics of an instrument. Describe the methods to obtain these characteristics.	4	CO2			
Q 5	Discuss the various methods for performing stability analysis of closed-loop control systems.	4	CO5			
	SECTION B					
(Answer in not more than 150 words)						
Q 6	Perform the mathematical modelling of a liquid flow system and hence obtain the transfer function and draw the block diagram.	10	CO2			
Q 7	Discuss the various types of controllers that can be used in a feedback control system.	10	CO2			
Q 8	Derive the transfer function of a first order system and hence find out its dynamic response to a periodic harmonic input.	10	CO3			
Q 9	a) For the system with block diagram as in Fig. 1, $G = \frac{1}{10D^2+3D}$ . If K = 50, K <sub>d</sub> = 1, K <sub>i</sub> = 0.5, find the steady state error when r = 0 and b = 5. <b>r</b> (t) <b>e K</b> (1+K <sub>d</sub> D + $\frac{k_i}{D}$ <b>b</b> (t) <b>g c G c f</b> (t) <b>f</b> (t)	10	CO4			

Semester : V Time : 03 hrs. Max. Marks : 100

	OR		
	b) For the system shown in Fig. 1, find the steady state error when r = 2 and b = 0.		
	SECTION-C		
Q 10	In the system of Fig. 2, the controlled variable is $h_c$ , the level in the tank. Input motion 'z' = 0.1h <sub>r</sub> , Port constant 'b' of hydraulic servomotor = 400 cm <sup>2</sup> /sec. Area $A = 2.5$ cm <sup>2</sup> . Area $A_T = 1.2$ m <sup>2</sup> , Inflow rate $q_{in} = Ky$ , $K = 2.0$ m/s <sup>2</sup> . Mass density ' $\rho$ ' of liquid = 1000 kg/m <sup>3</sup> . Fluid resistance 'R' = 10000 Ns/m <sup>5</sup> .	20	CO4
	(Internal Choice of Q. 10) Draw the closed-loop frequency response curve (polar plot) for the block diagram shown in Fig. 1. Take $K = 1$ , $K_d = 0$ , $K_i = 0$ , and $G = \frac{1}{10D^2+3D}$ . Ignore disturbance b(t).		
Q 11	A rectangular steel rod width b and depth d is supported at its ends and loaded at its centre by load W. If the length of the rod between the supports is l and $y_c$ is the deflection at the centre, then $y_c = \frac{Wl^3}{4Ebd^3}$ where E is the modulus of elasticity of elasticity. Measurement give $b = 4.942 \pm 0.042 \text{ cm}$ $d = 5.250 \pm 0.025 \text{ cm}$ $l = 1.000 \pm 0.5 \text{ cm}$ $y_c = 2.622 \pm 0.25\% \text{ of } y_c \text{ mm}$	20	CO2

W = 15000 N (exact)	
(a) Determine the nominal value of the modulus of elasticity.	
(b) Determine the percentage uncertainties in the various measured quantities.	
(c) Compute the percentage uncertainty in the modulus of elasticity.	